

Differentially Private Best Subset Selection Via Integer Programming

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Problem Definition and Motivation

- Best Subset Selection (BSS):

$$\min_{\beta \in \mathbb{R}^p} \|\mathbf{y} - \mathbf{X}\beta\|_2^2 \quad \text{s.t.} \quad \|\beta\|_0 \leq s, \|\beta\|_2^2 \leq r^2 \quad (1)$$

- An important methodological problem
- Can be computationally challenging
- Recent work uses Mixed Integer Programming (MIP) to solve large BSS instances [1,2].

- (ε, δ) -Differentially Private (DP) Algorithm \mathcal{A} :

$$\mathbb{P}(\mathcal{A}(\mathcal{D}) \in K) \leq e^\varepsilon \mathbb{P}(\mathcal{A}(\mathcal{D}') \in K) + \delta$$

for any measurable event $K \subset \text{range}(\mathcal{A})$ and for any pair of neighboring datasets \mathcal{D} and \mathcal{D}' .

- **Goal:** Designing an $(\varepsilon, 0)$ -DP algorithm for variable selection (i.e., optimal location of nonzeros) in the BSS.

- **Current Algorithms for DP-BSS:**

- convex relaxations, private Lasso [3, 4, 5, 6]
- Markov chain mixing [7]

- Recent work has shown that (non-private) BSS can have favorable practical and theoretical properties over its convex relaxations under certain settings [8,9].

- **Our Proposal:** A new DP-variable selection method for the **original BSS problem (1)**. We use techniques from MIP to scale-up our selection procedure.

Problem Formulation

- Define our outcome set as $\mathcal{O} = \{S \subseteq [p] : |S| = s\}$ and the objective for each S as:

$$\mathcal{R}(S, \mathcal{D}) = \min_{\beta \in \mathbb{R}^{|S|}} \|\mathbf{y} - \mathbf{X}_S \beta\|_2^2 \quad \text{s.t.} \quad \|\beta\|_2^2 \leq r^2$$

- The global sensitivity is

$$\Delta = \max_{S \in \mathcal{O}} \max_{\mathcal{D}, \mathcal{D}' \text{ are neighbors}} \mathcal{R}(S, \mathcal{D}) - \mathcal{R}(S, \mathcal{D}')$$

Lemma (*): If $|y| \leq b_y$ for $y \in \mathcal{Y}$, and $\|\mathbf{x}\|_\infty \leq b_x$ for $\mathbf{x} \in \mathcal{X}$. Then, $\Delta \leq 2b_y^2 + 2b_x^2 r^2 s$.

DP Algorithm

- $\forall k \in [R]$ where $R \ll \binom{p}{s}$, define

$$\hat{S}_k(\mathcal{D}) \in \arg \min_S \mathcal{R}(S, \mathcal{D}) \quad \text{s.t.} \quad S \subseteq [p], |S| = s,$$

$$S \neq \hat{S}_i(\mathcal{D}), \forall i \in [k-1]$$

- $\hat{S}_k(\mathcal{D})$ can be obtained by solving a series of MIPs:

$$\min_{\mathbf{z}^{(k)}, \beta^{(k)}, \boldsymbol{\theta}^{(k)}} \|\mathbf{y} - \mathbf{X}\beta^{(k)}\|_2^2$$

$$\text{s.t.} \quad \beta^{(k)}, \boldsymbol{\theta}^{(k)} \in \mathbb{R}^p, \mathbf{z}^{(k)} \in \{0, 1\}^p, \boldsymbol{\theta}^{(k)} \geq 0, \sum_{i=1}^p z_i^{(k)} = s,$$

$$\sum_{i=1}^p \theta_i^{(k)} \leq r^2, (\beta_i^{(k)})^2 \leq \theta_i^{(k)} z_i^{(k)} \quad \forall i \in [p]$$

$$\sum_{i \in \hat{S}_j(\mathcal{D})} z_i^{(k)} \leq s - \frac{1}{2}, \quad j = 1, \dots, k-1.$$

where $\hat{S}_k(\mathcal{D}) = \{i : \hat{z}_i^{(k)} \neq 0\}$.

- Off-the-shelf solvers such as Gurobi can obtain globally optimal solutions to the MIP above for moderately-sized instances.

Define the following probability distribution:

$$\mathbb{P}_0(k) \propto \begin{cases} \exp(-\varepsilon \mathcal{R}(\hat{S}_k(\mathcal{D}), \mathcal{D}) / (2\Delta)) & \text{if } k \leq R \\ \binom{p}{s} \exp(-\varepsilon \mathcal{R}(\hat{S}_R(\mathcal{D}), \mathcal{D}) / (2\Delta)) & \text{if } k = R+1 \end{cases}$$

Algorithm BSS with DP guarantees

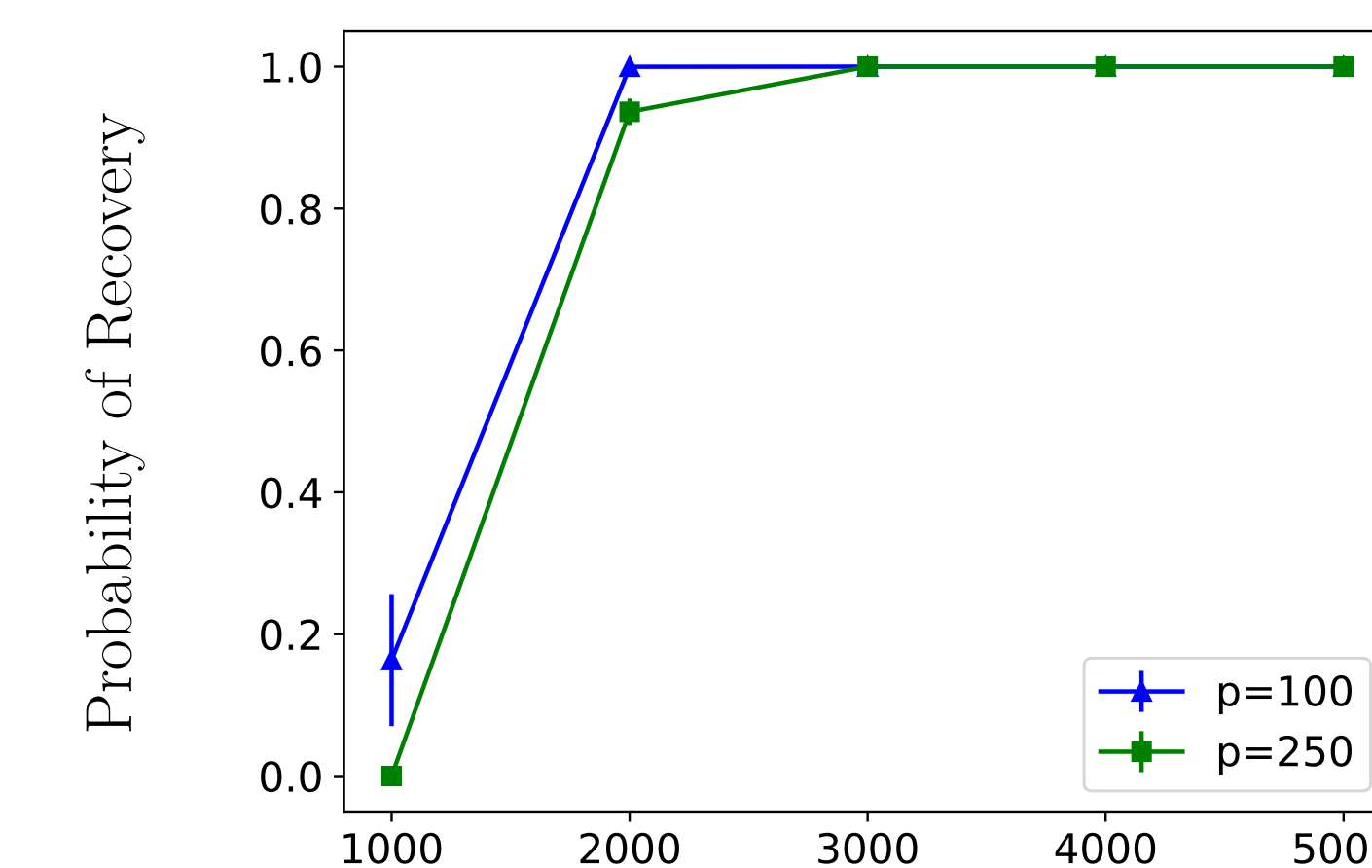
- 1: **procedure** $\mathcal{M}(\mathcal{D}, b_x, b_y, r, R, T)$
- 2: **Clip** \mathbf{X}, \mathbf{y} to b_x, b_y , respectively, as in (*). Take Δ as in (*). Form \mathbb{P}_0 .
- 3: **Draw** $a(\mathcal{D}) \sim \mathbb{P}_0$
- 4: **if** $a(\mathcal{D}) \leq R$ **then**
- 5: **return** $\hat{S}_{a(\mathcal{D})}(\mathcal{D})$
- 6: **else**
- 7: **return** a uniform draw from $\{\hat{S}_k : k > R\}$

Theorem 1: Suppose $1 < R < \binom{p}{s}$. The procedure \mathcal{M} is $(\varepsilon, 0)$ -DP. Moreover, $\mathbb{P}(\mathcal{M}(\mathcal{D}) = \hat{S}_1(\mathcal{D})) \geq \mathbb{P}_0(1)$.

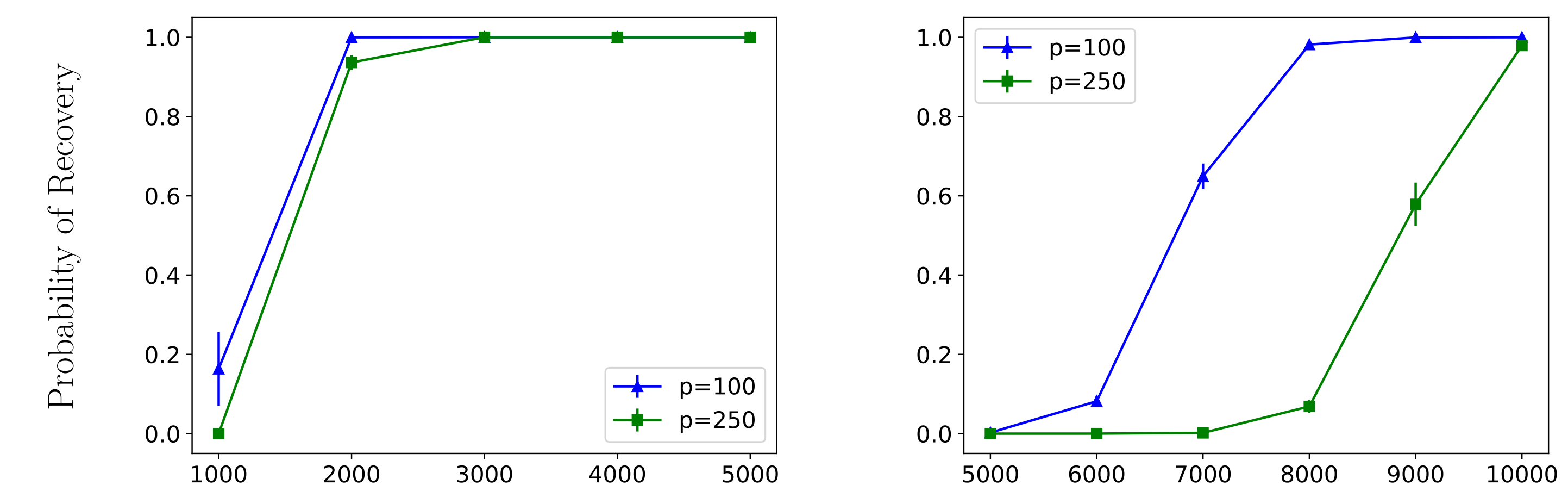
- No need to sample from a non-uniform distribution with exponentially large support.
- Intuition: “Flatten” the tail of exponential mechanism [10].

Numerical Experiments

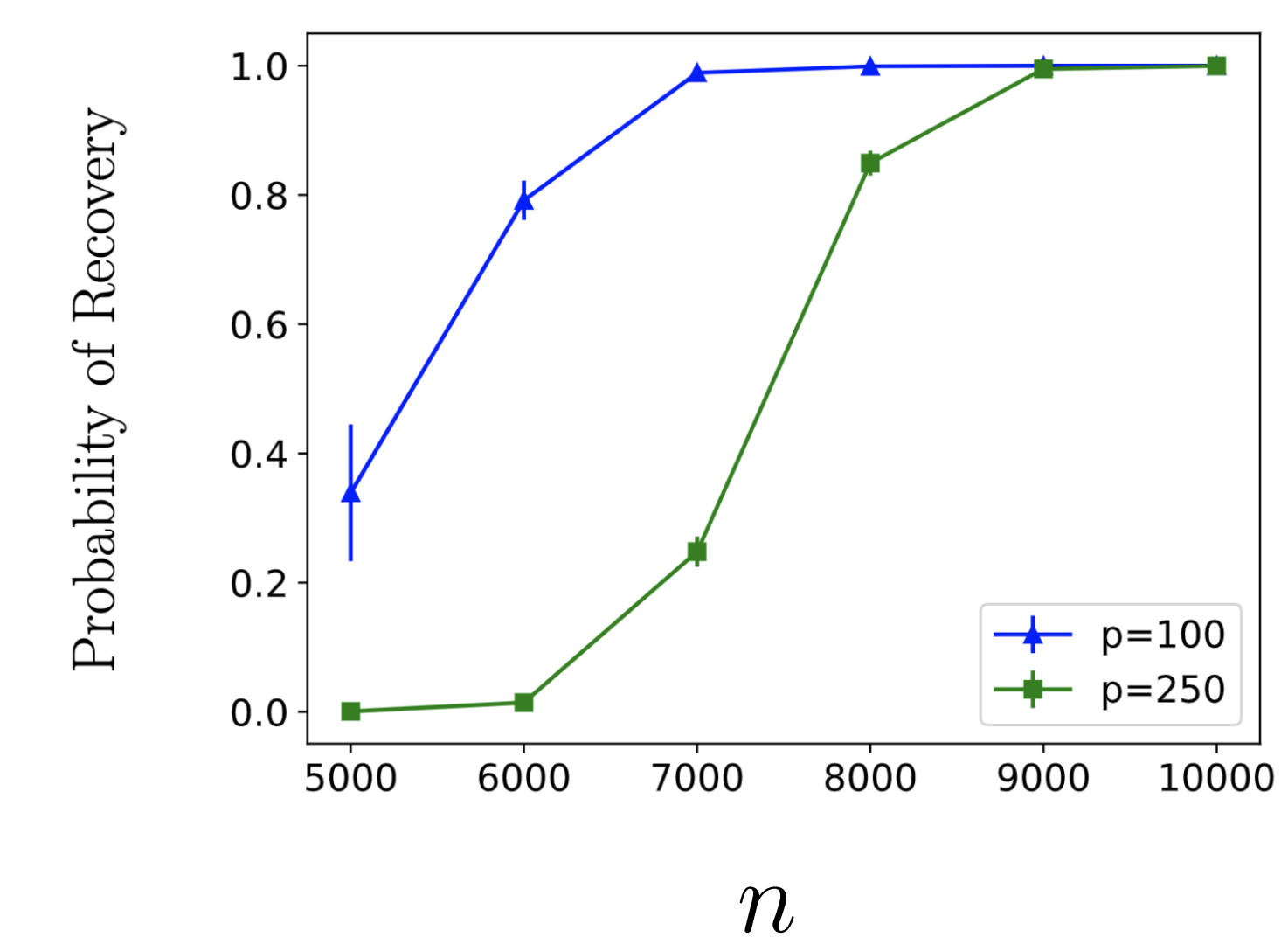
SNR = 2, $\varepsilon = 5, s = 5$



SNR = 5, $\varepsilon = 2, s = 7$



SNR = 5, $\varepsilon = 1, s = 5$



Conclusion

- A new pure-DP algorithm for variable selection in BSS (1).
- We use MIP techniques to develop our DP variable selection algorithm.
- Good statistical performance and scalable to $p \approx 250$.

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